

6 Axis Articulated Arc Welding Robots

# TS/TM/TL (GIII) Series







# Combination with Full Digital Welding Power Source Achieves Stable and High Quality Welding







■ Manipulator Lineup (as of November 2019)

	1 \			,						
	TS s	eries		TM series					TL series	
	800	950	1100	1400	1600	1800	2000	1800	2000	
Separate	_	_	0	0	0	0	0	_	_	
Through-Arm	0	0	0	0	0	0	0	_	_	
External	0	0	0	0	_	_	_	0	0	
Payload	8	kg	6	kg	4 kg	6	kg	8 kg	6 kg	

# A variety of features specialized for arc welding

# Feature (TM/TL) Enhanced Basic Performance

# **Increased Motion Speed**

TM-1400: Speed of main 3 axes increased by 22 % on average. (approx. 42°/s more than TA type)

## **Extended Reach**

TM-1400: 1 437 mm (63 mm more than TA type)



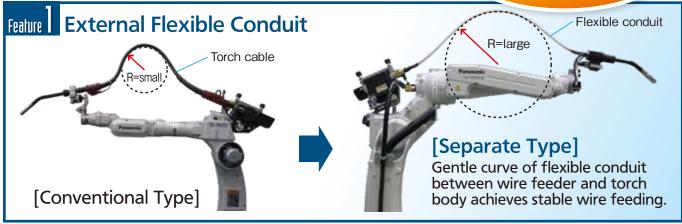


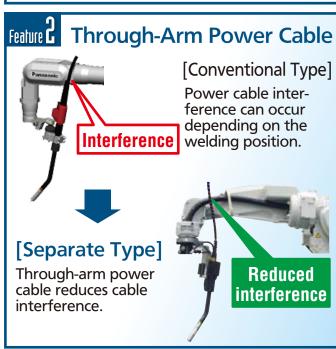
In addition to Through-Arm Type and External Type,

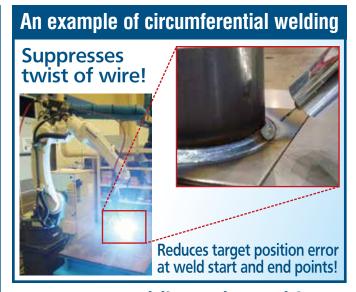
# A third choice—Separate Type (TM series)

Revolutionary new type of arc welding robot with advantages of both Through-Arm Type and External Type.

# High Wire Feedability Less Gable Interference







New type welding robot achieves even higher quality welds.



# Advanced Hardware and Software Improve Performance

# **GIII** controller with high performance

- Faster CPU reduces start-up time to **about 30 seconds**. (50 % reduction from previous model)
- Optional memory allows storing 800,000 teaching points in addition to the standard 40,000 points.



# Teach pendant with enhanced operability

## Operating function key



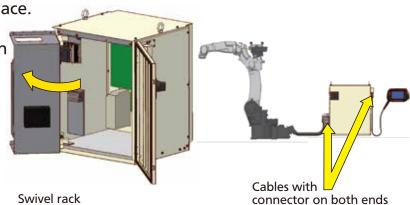
Same basic operation procedure with G2 Series model Easy to use Windows based operation

- ●Light weight design under 1 kg (0.99 kg) giving you less stress during teaching
- Liquid crystal LED back light improving impact resistance
- USB and SD memory interface realizing great expandability
- Increased number of function keys (four to eight),
   enabling same action with less key strokes during teaching

# Improved maintainability

Swivel rack in the case makes maintenance easy and saves space.

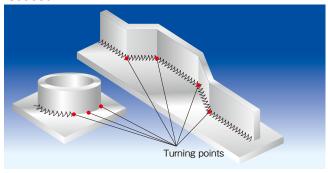
Cables with connectors on both ends reduce Cable exchange time.



# Standard Features

#### Weaving Function (6 patterns)

You just have to teach the starting point, amplitudes, turning points and ending point. Teaching time will be reduced.



#### Parallel Shift + RT Axis Rotating

Teaching time of same workpieces is reduced.



## Torch Angle Display (Teach Pendant)



Torch angle is displayed on the screen, making it possible to reduce teaching time and obtain consistent bead appearance.

#### Overlap Function (CO<sub>2</sub>/MAG welding)

In case of interruption during welding, the torch is stepped back by reboot and resumes the welding from the welding end point.



### Arc Start Retry (CO<sub>2</sub>/MAG welding)

Detecting a failure of arc start, the robot automatically starts arc ignition again.



# Optional Features

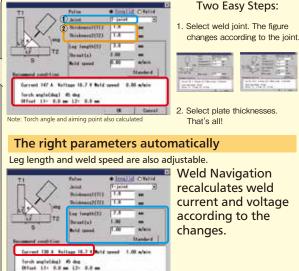
#### "Weld Navigation" allows easy parameter setting

Easy setting with Teach Pendant



Rich welding parameter database developed through our long experience

"Weld Navigation" reduces parameter setting time.



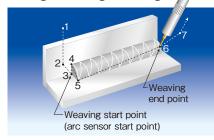
Notes: •Parameters by Weld Navigation are guideline only and do not guarantee welding result.
•Consult us for material and processes available with Weld Navigation.

# Weld Navigation

Model: 350GZ4

#### Arc Sensor

The sensor corrects deviation from the taught weld line by detecting weld current changes during weaving welding.



#### **Touch Sensor**

The welding wire touches the workpiece and compensates a workpiece position error, which reduces jig costs.



#### **Expansion**

#### Multi-Mechanism Control

Controls maximum 6 groups of robots and external axes in parallel.

#### Cooperative Multi-Robot Control

Allows cooperative control between two robots.

#### Units

- ·Analog I/O Expansion Unit ·Relay Connection Unit
- ·Terminal Block Conversion Unit ·External Power Input Unit

# Robot System (GIII) Welding Power Source Achieves Stable and High Quality Welding

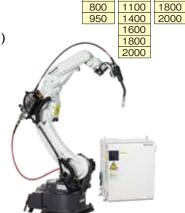
# **Combination with Full Digital Welding Power Source Achieves**

# CO<sub>2</sub>/MAG/MIG welding robot system selectable to fit your application

Full Digital CO<sub>2</sub>/MAG welding machines GZ4 series



(Super-imposition Control)





500GZ4YĀA

350GZ4YA

Equipped with TAWERS's SP Control Praised by Many of Our Customers

# SP-MAG benefits:

- Reduced spatter (Reduced removal work)
- Shorter short-circuit cycle suited for high speed welding
- Shorter arc length for good bead appearance

## Good bead appearance and low spatter even in high speed welding Note: Optional parts are necessary to connect GZ4 to robot.

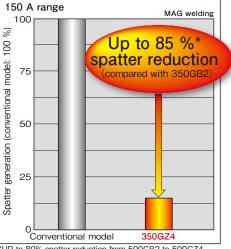
MAG welding (220 A) Joint: Fillet • Base metal: Mild steel SPCC (t2.3 mm) • Weld current: 220 A Weld speed: 100 cm/min • Wire size: 1.2 mm (YM-50MT) Shielding gas: MAG (80 % Ar + 20 % CO<sub>2</sub>)

### MIG welding (180 A)

- Joint: Fillet Base metal: SUS308(t1.5 mm) Weld current: 180 A Weld speed: 80 cm/min Wire size: 1.2 mm (Y308Lsi) Shielding gas: MIG (98 % Ar + 2 % O<sub>2</sub>)

■Spatter generation

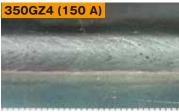




\*UP to 80% spatter reduction from 500GB2 to 500GZ4 in 250 A range

Conventional model (150 A)





- · Joint: Fillet · Base metal: Mild steel SPCC (t2.3 mm) · Weld current: 150 A
- · Weld speed: 50 cm/min · Wire size: 1.2 mm (YM-50MT)
- Shielding gas: MAG (80 % Ar + 20 % CO<sub>2</sub>)



CO<sub>2</sub>/MAG/MIG **Welding Machine** Lineup for High Quality Welds







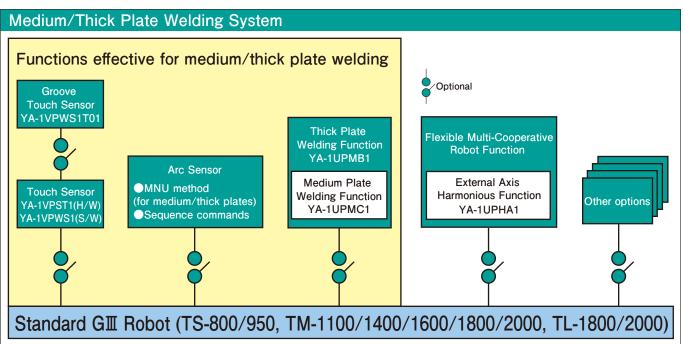


350VR1YA1 500VR1YA1

400VP1YA1

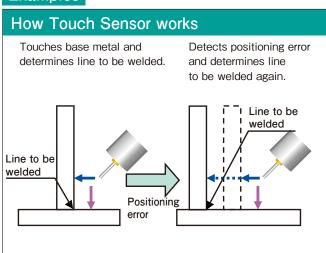


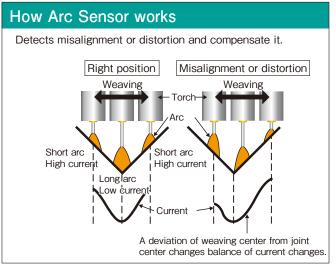
# Optional Functions Effective for Medium and Thick Plates

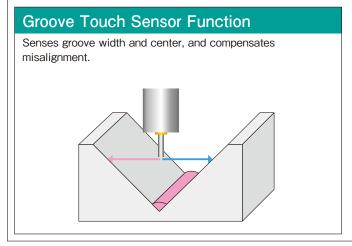


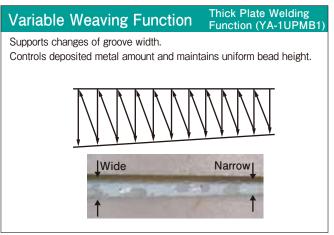
#### Consult us for details.

#### **Examples**











# **High Quality Welding**

# Robotic TIG welding system selectable to fit your application

#### Model Selection Guide

Туре	Material	Filler wire dia. (mm)	Welding power source	Robot	
Autogenous	Stainless steel	_	300BZ3	TS-800 TS-950	
TIG (no filler)	Stainless steel Aluminum	_	300BP4 500BP4	TM-1100 TM-1400 TL-1800	
Filler TIG	Stainless steel	1.2	300BZ3	TS-800 TS-950	
Filler TIG	Stainless steel Aluminum	1.2	1.2 300BP4 500BP4	TM-1100 TM-1400 TL-1800	
Rotary filler TIG	Stainless steel	1.2	300BZ3	TL-1800	
	Stainless steel Aluminum	1.2	300BP4 500BP4	112-1000	

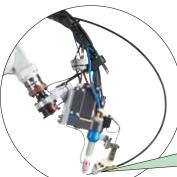


<sup>·</sup> An external axis controller is necessary for rotary filler TIG welding.



Rotary filler TIG Welding Robot System TL-1800GII

# Features of Rotary TIG Filler Unit



- Optimum welding position
- High precision filler wire feed
- Improved workpiece accessibility

Filler wire tip position is adjustable in all directions

# TIG welding torch lineup



YT-TCT201

- · Air-cooled



YT-TCT401

- · Water-cooled
- · 35 % duty cycle at 200 A · 60 % duty cycle at 400 A

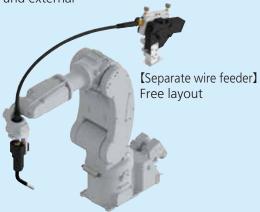


# Small Type Arc Welding Robots



# Various welding styles

[TW axis: Hollow arm] Torch type selectable between through-arm and external



# Improve small work productivity

Space saving 48 % smaller footprint (example of one customer, compared with our TM-1100)

Floor/Wall/Ceiling mount (Ceiling mount type is special specification.)

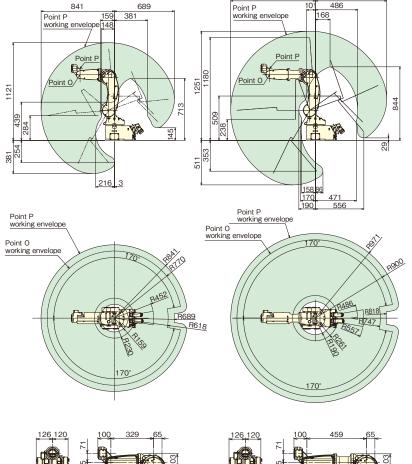
High speed despite 8 kg payload Maximum motion speed: 540%s (average for all axes)

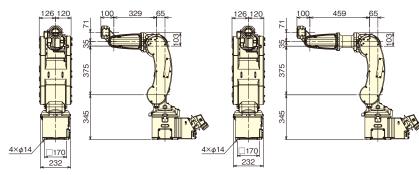
# **Dimensions & Work Envelope**

For working envelope of point O, consult us.

**Short Type** TS-800 **Short Type** TS-950

(Unit: mm)





## ■ Manipulator General Specifications

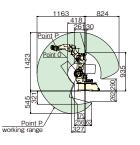
	<u> </u>					
Model		TS-800	TS-950			
Type		Short arm	Short arm			
Structu	re	6 axis ar	ticulated			
Payload		81	kg			
Maximu	ım Reach	841 mm	971 mm			
Minimu	m Reach	159 mm	190 mm			
Working	g Range	682 mm	781 mm			
	RT (Rotating Trunk)	326°/s				
	UA (Upper Arm)	326°/s				
Max. Motion	FA (Forearm)	510°/s				
Speed	RW (Rotating Wrist)	518°/s				
	BW (Bending Wrist)	518°/s				
	TW (Twisting Wrist)	1 040°/s				
Position	Repeatability	±0.05 mm				
Motors	Total Power	2 100 W				
IVIOLOIS	Brakes	All axes				
Mountii	ng	Floor/Ceiling*1/Wall*2				
Weight		55 kg	56 kg			

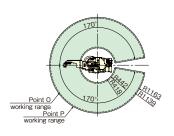
<sup>\*1:</sup> Ceiling mount type is factory optional.

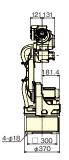
\*2: •Setting by service personnel is necessary. •Working range of RT axis is limited.

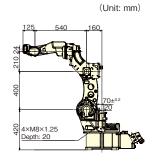
# **Dimensions & Work Envelope**



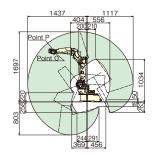


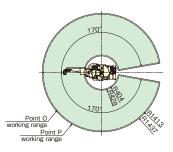




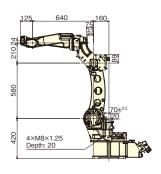




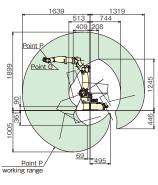


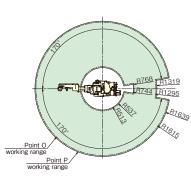


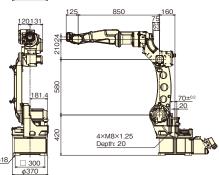




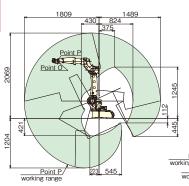


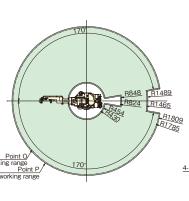


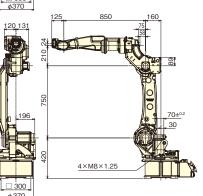




# Long Type TM-1800





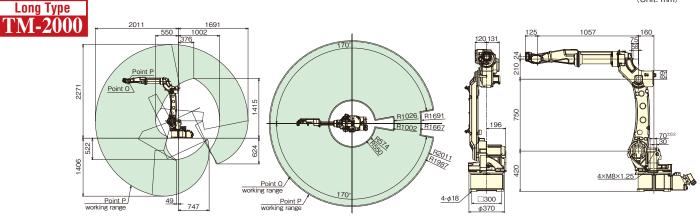


#### ■ Manipulator General Specifications

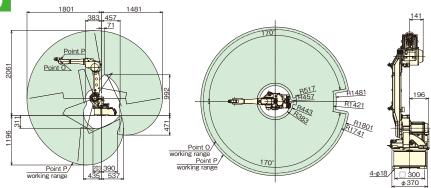
Manipulator deneral Specifications										
Model		TM-1100	TM-1400	TM-1600	TM-1800	TM-2000	TL-1800	TL-2000		
Type		Short arm	Standard arm	Middle arm	Long arm	Long arm	Long arm	Long arm		
Structur	re		6 axis articulated							
Payload		6 kg		4 kg	6 kg		8 kg	6 kg		
Maximu	ım Reach	1 163 mm	1 437 mm	1 639 mm	1 809 mm	2 011 mm	1 801 mm	1 999 mm		
Minimu	m Reach	418 mm	404 mm	513 mm	430 mm	550 mm	383 mm	491 mm		
Working	g Range	745 mm	1 033 mm	1 126 mm	1 379 mm	1 461 mm	1 418 mm	1 508 mm		
	RT (Rotating trunk)	22!	5%s	210%s	195%s		195%s			
	UA (Upper arm)	22!	5%s	210%s	197%s		197%s			
Max. Motion	FA (Forearm)	225%s		215%s	205%s		205%s			
Speed	RW (Rotating wrist)	42!	5%s	425%s	42	5%s	38	5%s		
	BW (Bending wrist)	425	5%s	425%s	42	5%s	37	5%s		
	TW (Twisting wrist)	629	9%s	629%s	62	9%s	62	4%s		
Position	Repeatability	±0.08 mm		3 mm		±0.10 mm	±0.08 mm	±0.15 mm		
Motors	Total Power		3 400 W		4 700 W		5 050 W			
IVIOLOIS	Brakes				All axes	All axes				
Mounting					Floor / Ceiling*		·			
Weight		156 kg	170 kg	180 kg	215 kg	217 kg	215 kg	216 kg		

# **Dimensions & Work Envelope**

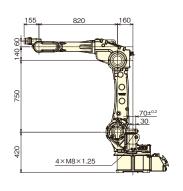
(Unit: mm)

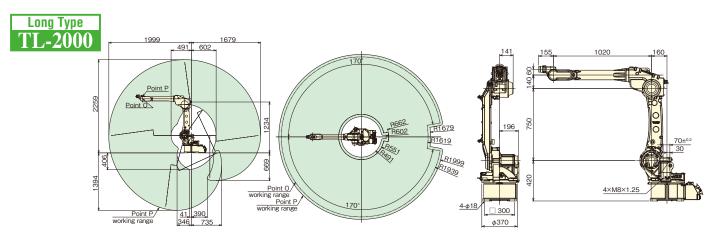


# Long Type TL-1800

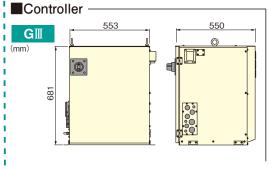


Model





# **■**Controller Specifications

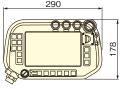


	Dimensions*1	W 553 mm x D 550 mm x H 681 mm	
Weight* <sup>2</sup> 60 kg			
Memory Capacity 40 000 points			
Position Control Software servo control			
External Memory Teach Pendant: one SD memory card slot Two USB 2.0 ports (USB 2.0 Hi-Speed not supp			
	Control Axes	6 axes simultaneously (Max.27 axes)	
		Input: 40 points (Optionally expandable up to 2048 points) Output: 40 points (Optionally expandable up to 2048 points)	
Input Power 3 phase, 200/220 VAC±20 V, 3 kVA, 50/60 Hz			

GⅢ

■Teach pendant

**G**∭ (mm)



76	
M N	

<sup>\*1:</sup> Protruding portions not included.

<sup>\*2:</sup> Teach pendant and connection cables not included.

# Large Robot Series (GII Controller)

**Great material handling capability! Coordinated multi-robot movement** for flexible system without jig.





Coordinated movement with WGII/GII robot(s)

Allows to build flexible system without jig.

Maximum configuration: ·Arc welding robot x 2 ·Large robot x 1

GⅢ controller for large robots Same operation, maintenance and options as conventional robots

## ■ Manipulator General Specifications

Model			YS-080GⅢ	HS-220GⅢ	
Type	Type		6 axis articulated robot		
Payloa	d		80 kg	220 kg	
	RT (Rota	ating trunk)	±180 °	±178°	
	UA (Upp	per arm)	-80 ° ~ +155 °	-65 ° ~ +80 °	
	FA (Forearm)	Referenced from Horizontal	-140 ° ~ +230 °	-130 ° ~ +230 °	
Working		Referenced from upper arm	-80 ° ~ +180 °	-73° ~ +190°	
Range	RW (Rot	ating wrist)	±360 °	±360 °	
	BW (Ber	nding wrist)	±125°	±128°	
	TW (Twi	sting wrist)	±360 °	±360 °	
	RT (Rota	ating trunk)	170%s	120%s	
Max.	UA (Upp	per arm)	140%s	105%s	
	FA (Fore	arm)	160%s	110%s	
Motion		ating wrist)	230%s	145%s	
Speed	BW (Ber	nding wrist)	230%s	145%s	
	TW (Twi	sting wrist)	350%s	220%s	
Weigh	t	645 kg 955 kg		955 kg	

# **3m ARM WELDING ROBOT**

● Conventional technologies "GIII controller & Wire feeder" are adopted High quality welding in combination with Full Digital welding power source

HS-220GⅢ

 Realize the simple system (External axis is unnecessary)

YS-080GⅢ

Suitable for larger work (application example)



for Beam axle type suspension system [Maximum Reach for Welding: 3 281 mm]



#### ■ Manipulator General Specifications

Model		HH020L	
Payload		20 kg	
Structure		6 axis articulated	
	RT (Rotating trunk)	±180 °	
	UA (Upper arm)	+180 ° ~ -65 °	
Working	FA (Forearm)	+260 ° ~ -160 °	
Range	RW (Rotating wrist)	±195°	
	BW (Bending wrist)	±135 °	
	TW (Twisting wrist)	±360 °	
	RT (Rotating trunk)	175%s	
Max.	UA (Upper arm)	175%s	
Motion	FA (Forearm)	180%s	
Speed	RW (Rotating wrist)	360%s	
	BW (Bending wrist)	380%s	
	TW (Twisting wrist)	600%s	
Position F	Position Repeatability ±0.15		
Maximum	n Reach	3 281 mm	
Weight(A	approx.)	535 kg	

# Tilt-Rotate Positioners High-Speed Type R Series



Two types available: 300 kg and 500 kg payload

- 1.8 times faster maximum speed compared with the conventional models.
- ullet Smallest-in-class footprint of 780 imes 500 mm. (300 kg payload model)
- Easier installation with three selectable cable outlet positions.

#### ■Specifications

Name		Positioner unit		
Model		YA-1RJC62	YA-1RJC72	
Applicable Robot		Panasonic robots TM/TL series with GⅢ/WGⅢ controller		
Payload		300 kg	500 kg	
Max. Speed	Rotation	190.0°/s (31 r/min)	165.0°/s (27 r/min)	
iviax. Speed	Tilt	125.5°/s (20 r/min)	90.0°/s (15 r/min)	
Operating	Rotation	-3 600° to +3 600° (with multi-rotation data reset function		
Range	Tilt	-135° to +135°		
Allowable	Rotation	323 N·m	392 N·m	
Moment	Tilt	882 N·m	1 274 N·m	
Position Repeatal	oility	±0.05 mm (R=250 mm)		
Hollow Shaft Diar	meter	55 mm		
Allowable Welding Current		500 A @ 60 % duty cycle		
Weight		285 kg		
Applicable Weldin	g Process	CO <sub>2</sub> /MAG/MIG/TIG		
External Axis Conti	roller Type	Internal/External		

# Single-axis positioners







#### ■Specifications

Name	Positioner unit				
Model	YA-1RJB12	YA-1RJB22	YA-1RJB32		
Applicable Robot	Panasonic robots	TM/TL series with GI	I/WGII controller		
Payload	250 kg	500 kg	1 000 kg		
Max. Rotational Speed	190°/s (31.6 r/min)	120°/s (20 r/min)	120°/s (20 r/min)		
Operating Range	-3 600° to +3 600°	(with multi-rotation o	data reset function)		
Allowable Torque	196 N•m	490 N•m	1 470 N•m		
Allowable Moment	1 470 N•m	1 470 N•m	6 125 N·m		
Position Repeatability	±0.05 mm (R=250)				
Hollow Shaft Diameter	55 mm	55 mm	75 mm		
Brakes		Provided			
Allowable Welding Current	500 A @ 60 % duty cycle				
Weight	125 kg		255 kg		
Applicable Welding Process	CO <sub>2</sub> /MAG/MIG/TIG				
External Axis Controller Type	Internal/I	External	External		

# RJB 12/22





### **Production Management Function** Real-Time Monitoring on PC.

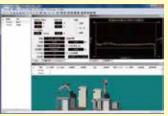
# Effective for Monitoring Robot Operation and Production Progress.





HUB









#### Monitors Teach Pendant (TP) screen in real time, whitch allows to share information away from welding site.

# Robot operation monitoring

Monitors robot movement and welding waveform in real time, which allows to improve welding posture and conditions.



11111





- · An optional license is necessary for each robot.
- · The network environment and devices (including PC) must be prepared by the customer.
- · Up to 10 robots can be connected to one PC.
- It is not possible to connect to the external network (e.g., connection from factory LAN to the Internet).
- WG II, WGH III, and G III controllers of software version 20.00 or later are applicable. (TIG is not supported.)

# **FA Technical Centers**

# Feel the excellent performance of TAWERS













Consulting



FATC(Dusseldorf)

• Other FATC: Wuhan, Queretaro, Bowin, Jakarta, Hanoi, Detroit, Columbus, Sao Paulo

We support development of highly skilled welding operators.

Workshops:

- Robot
- MAG/MIG
- TIG
- · Special training

**Process Development** 





Case Examples:

- · New factory weld processing
- · Improvement of existing processes
- · Develop new welding solutions

#### **Professional staff offer** technical solutions.

Qualifications:

- Welding coordination personnels (including first class)
- JIS qualified welding operators
- Metal materials inspectors
- International welding license holders



# We provide products that are friendly to the environment.

As an earth-friendly company, Panasonic Corporation discourages the use of hazardous substances in our products. The products of Panasonic Corporation comply with the European RoHS directive.



Safety precautions

Before attempting to use any welding product always read the manual to ensure correct use.

#### Panasonic Connect Co., Ltd

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