MEMS gyro sensor for navigation using an inclined detection axis. The inclination of the unit can be changed. This microsensor has high precision and reliability due to the sealing around the bear chip IC and MEMS silicone based tuning fork, formed with piezo-electric thin film directly on the surface.

**Features**
- Compact, Low-height 5.0 mm max., Low-profile 4.3 mm
- SMD type
- 5.0 V.DC operating voltage
- Detection axis 0 deg / 20 deg inclination (Refer to the diagram on the right)
- Analog Output (Ratio-metric output)
- RoHS compliant

**Recommended Applications**
- Detects the direction of movement for car-navigation
- Detects the posture control for robot

**Ratings**

<table>
<thead>
<tr>
<th><strong>Electrical Characteristics</strong></th>
<th><strong>Environmental Characteristics</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Voltage Range</td>
<td>Low Temperature Operation</td>
</tr>
<tr>
<td>5.0 V.DC±0.25 V.DC</td>
<td>−40 °C for 72 h</td>
</tr>
<tr>
<td>Operating Temperature Range</td>
<td>High Temperature Operation</td>
</tr>
<tr>
<td>−40 °C to +85 °C</td>
<td>+85 °C for 120 h</td>
</tr>
<tr>
<td>Zero Point Output</td>
<td>Thermal Shock</td>
</tr>
<tr>
<td>(−40 °C to +85 °C)</td>
<td>−40 °C to +85 °C for 25 cycles</td>
</tr>
<tr>
<td>2.5 V.DC ± 0.4 V.DC</td>
<td>Heat and Damp Cycling Test</td>
</tr>
<tr>
<td>Sensitivity (Z axis)</td>
<td>−40 °C to +60 °C 90 %RH for 5 cycles</td>
</tr>
<tr>
<td>(−40 °C to +85 °C)</td>
<td>Life (Operating Durability)</td>
</tr>
<tr>
<td>25 mV/ °/ s</td>
<td>2 Hz, 1×10⁷ cycles</td>
</tr>
<tr>
<td>Dynamic Range</td>
<td></td>
</tr>
<tr>
<td>±60 °/s</td>
<td></td>
</tr>
<tr>
<td>Frequency Response</td>
<td></td>
</tr>
<tr>
<td>−4.0 dB to 0 dB</td>
<td></td>
</tr>
<tr>
<td>Output Noise</td>
<td></td>
</tr>
<tr>
<td>&lt; 10 mV</td>
<td></td>
</tr>
</tbody>
</table>

Design and specifications are each subject to change without notice. Ask factory for the current technical specifications before purchase and/or use. Should a safety concern arise regarding this product, please be sure to contact us immediately.

Aug. 2015
Dimensions in mm (not to scale)

- **Dimensions in mm (not to scale)**
  - **X-axis**
  - **Y-axis**
  - **Z-axis**

- **Terminal**
  - ① Reserved 1
  - ② Reserved 2
  - ③ Vout
  - ④ GND
  - ⑤ REG
  - ⑥ Vcc
  - ⑦ Reserved 3
  - ⑧ Reserved 4
  - ⑨ CAP
  - ⑩ CAP

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Should a safety concern arise regarding this product, please be sure to contact us immediately.

00 Aug. 2015
Gyro Sensors for General-Purpose SMD, Inclined Detection Axis Type

Type: EWTS8RD□□□/EWTS8RS□□□

MEMS gyro sensor for navigation using an inclined detection axis. The inclination of the unit can be changed. This microsensor has high precision and reliability due to the sealing around the bear chip IC and MEMS silicone based tuning fork, formed with piezo-electric thin film directly on the surface.

**Features**

- Compact, Low-height 5.0 mm max., Low-profile 4.3 mm
- SMD type
- 3.3 V.DC operating voltage
- Detection axis 0 deg / 20 deg inclination (Refer to the diagram on the right)
- Digital Output : SPI communication
- RoHS compliant

**Recommended Applications**

- Detects the direction of movement for robot-cleaner
- Detects the direction of movement for car-navigation
- Detects the posture control for robot

**Ratings**

<table>
<thead>
<tr>
<th><strong>Electrical Characteristics</strong></th>
<th><strong>Environmental Characteristics</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Voltage Range</td>
<td>Low Temperature Operation</td>
</tr>
<tr>
<td>3.3 V.DC±0.1.65 V.DC</td>
<td>–40 °C for 72 h</td>
</tr>
<tr>
<td>Operating Temperature Range</td>
<td>High Temperature Operation</td>
</tr>
<tr>
<td>–40 °C to +85 °C</td>
<td>+85 °C for 120 h</td>
</tr>
<tr>
<td>Zero Point Output</td>
<td>Thermal Shock</td>
</tr>
<tr>
<td>(–40 °C to +85 °C)</td>
<td>–40 °C to +85 °C for 25 cycles</td>
</tr>
<tr>
<td>Sensitivity (Z axis)</td>
<td>Heat and Damp Cycling Test</td>
</tr>
<tr>
<td>(–40 °C to +85 °C)</td>
<td>–40 °C to +60 °C 90%RH for 5 cycles</td>
</tr>
<tr>
<td>Dynamic Range</td>
<td>Life (Operating Durability)</td>
</tr>
<tr>
<td>±150 °/s</td>
<td>2 Hz, 1×10⁷ cycles</td>
</tr>
<tr>
<td>Frequency Response</td>
<td></td>
</tr>
<tr>
<td>–4.0 dB to 0 dB</td>
<td></td>
</tr>
<tr>
<td>Output Noise</td>
<td></td>
</tr>
<tr>
<td>&lt; 20 LSB</td>
<td></td>
</tr>
</tbody>
</table>
Gyro Sensors for General-Purpose/ EWTS8RD/ EWTS8RS

### Dimensions in mm (not to scale)

![Diagram of sensor dimensions]

**Tolerance:** ±0.2 mm

**Terminal:**

<table>
<thead>
<tr>
<th>①</th>
<th>CSB</th>
</tr>
</thead>
<tbody>
<tr>
<td>②</td>
<td>SCLK</td>
</tr>
<tr>
<td>③</td>
<td>Reserved 1</td>
</tr>
<tr>
<td>④</td>
<td>GND</td>
</tr>
<tr>
<td>⑤</td>
<td>REG</td>
</tr>
<tr>
<td>⑥</td>
<td>Vcc</td>
</tr>
<tr>
<td>⑦</td>
<td>MISO</td>
</tr>
<tr>
<td>⑧</td>
<td>MOSI</td>
</tr>
<tr>
<td>⑨</td>
<td>CAP</td>
</tr>
<tr>
<td>⑩</td>
<td>CAP</td>
</tr>
</tbody>
</table>

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Jul. 2015
Gyro Sensors

Safety Precautions (Gyro sensor of General-Purpose/EWTS8R□□□□)

1. Soldering

(1) Thickness of Solder Paste (Recommendation) : 0.12 mm to 0.15 mm
(2) Flux : Use non-corrosive rosin, and alcohol based solvent with little chemical reaction.
(3) Pre-heat : Control the temperature on PWB to be under 180 °C and no longer than 120 s
(4) Reflow Soldering condition : The Maximum temperature on PWB is 260 °C
(5) Atmospheric Temperature : The atmospheric temperature should be under 300 °C
(6) Cooling : To avoid deterioration of the sensor due to heat, immediately cool the sensor with blown air.
(7) Number of times it can be Reflow Soldered : Once
(8) Hand soldering (recommendation) : a) Use a 20 W or less soldering iron at less than 350 °C
    b) Soldering time: within 3 s

2. Washing

Do not wash.

3. Handling

(1) Handle with care. Do not drop or apply any strong impact to the sensor this may degrade some performances.
(2) Do not store under the following conditions, they may degrade some performances and solderability.
    a) Relative humidity of more than 85 %
    b) Atmospheres of corrosive gas (Cl₂, H₂S, NH₃, NOₓ, SO₂ etc.)
    c) Long term storage of over 3 months after delivery
       Do not store the package under severe load and stress.

4. Pattern layout of the circuit board

See the following recommended pattern design. (mm)

<table>
<thead>
<tr>
<th>PART SIDE</th>
</tr>
</thead>
</table>

| Sensor outline |
| Center line of sensor |
| Tolerance : ±0.1 mm |

5. Layout

The sensor has a little zero point temperature drift due to surrounding conditions. Take this into consideration when determining the location of the sensor.

(1) Do not locate the sensor close to heat radiating objects such as power transistors.
(2) Do not locate the sensor where it can be affected by heat convection.
(3) Do not locate two or more sensors on the same PWB, otherwise periodical drift of zero point output may occur due to mutual interference by the vibration of each tuning fork in the sensor.

6. Vibration from outside

To prevent the PWB’s (mounted sensor) from resonating with external vibration, please consider following these guides for the design of your PWB.

(1) Take into consideration the location of other parts which may cause vibration.
(2) Do not allow the screws, which fix the circuit board to become loose.
   * Do a vibration test and carefully check the condition of the sensor attached to the unit.

Design and specifications are each subject to change without notice. Ask factory for the current technical specifications before purchase and/or use. Should a safety concern arise regarding this product, please be sure to contact us immediately.
7. Recommended Circuit

(1) EWTS8RD□□□/EWTS8RS□□□

C1: Design chip capacitor with good high frequency characteristic about 0.1 μF near the terminals of the sensor as possible in parallel as measure for EMS.
C2: Since the sensor does not have a power supply back up, insert a backup capacitor as an instantaneous power failure.
C3: Design chip capacitor 0.1 μF near the terminals of the sensor as possible.
∗ NC terminal of the sensor connects with nowhere on your PWB.

(2) EWTS8RN□□□/EWTS8RK□□□

C1: Design chip capacitor with good high frequency characteristic about 0.1 μF near the terminals of the sensor as possible in parallel as measure for EMS.
C2: Since the sensor does not have a power supply back up, insert a backup capacitor as an instantaneous power failure.
C3: Design chip capacitor 0.1 μF near the terminals of the sensor as possible.
C4: Design chip capacitor 0.1 μF near the terminals of the sensor as possible.
∗ NC terminal of the sensor connects with nowhere on your PWB.

(3) If the noise of the frequency near the integral multiple (especially odd times) of the vibrator drive frequency and detuning frequency (drive frequency-sense frequency) are impressed to a power supply line, the low frequency wave noise of the difference of the frequency of a power supply noise and the frequency of the integral multiple of the vibrator drive frequency will be amplified and outputted ten times by signal processing of an gyro sensor. Please avoid the connection which contains high frequency noises, such as LCD, in the same power supply.

Drive frequency: 42.8 kHz±1 kHz
Detuning frequency: 300 Hz to 1500 Hz

(4) Since it may be influenced by the radiation noise from the line containing many high frequency noises, such as a digital power supply and digital GND, please give me consideration of wiring.

8. Limited Warranty

(1) Customer acknowledges that the gyro Sensor (“Product”) delivered to Customer by Panasonic Corporation (“Panasonic”) is designed and manufactured by Panasonic, or its affiliates, only for the purpose of incorporation into Customer’s car navigation system (hereinafter called “Purpose”). Accordingly, Customer understands that Panasonic, or its affiliates, shall only guarantee the performance of the Product under the Product Specification for information to the extent such Product is used by Customer for the Purpose defined in this paragraph.

(2) Customer agrees that it shall, at its sole cost and responsibility, test and evaluate the performance of Customer’s system which incorporates the Product (hereinafter called “System”).

(3) Customer acknowledges that some failure mode, such that Product does not comply with this Specification in terms of Zero Point Output and/or Sensitivity or shows any unstable performance, should be observed depending on the characteristics of the System, or the environment at which such System is installed. Therefore, Customer shall design the System taking into account such influences.

(4) Customer agrees that Panasonic shall not be responsible for any loss or damage due to defective Product, including, but not limited to, economic loss, bodily injury or property damage, as far as Customer utilizes the Product for any purpose other than the Purpose defined in the above paragraph 8-1. Therefore, Customer shall ensure the “fail-safe” design of the System, if it deems necessary, to mitigate any such loss or damage.
MEMS Gyro Sensors for Rollover Detection
SMD type
Type: EWTS64G

This sensor is a gyro sensor for rollover detection which adopts the SMD type. A ceramic package contains a bare chip IC and a MEMS silicon tuning fork whose surface is formed directly by PZT elements. Moreover, self-diagnostic functions are embedded to achieve high reliability.

Features

- Compact, Low height 5 mm
- SMD type
- High durability against the crash impact or vibration
- 5 V operating voltage (Ratio-metric output)
- Built-in self diagnosis
- RoHS compliant

Recommended Applications

- Automotive rollover detection
- Various types of motion controls for industrial equipment

Ratings

<table>
<thead>
<tr>
<th>Electrical Characteristics</th>
<th>Environmental Characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Temperature Range</td>
<td>Low Temperature Operation</td>
</tr>
<tr>
<td>Storage Temperature</td>
<td>High Temperature Storage</td>
</tr>
<tr>
<td>Operating Voltage Range</td>
<td>High Temperature Operation</td>
</tr>
<tr>
<td>Zero Point Voltage (–40 °C to +95 °C)</td>
<td>Thermal Shock</td>
</tr>
<tr>
<td>Sensitivity (–40 °C to +95 °C)</td>
<td>Mechanical Shock</td>
</tr>
<tr>
<td>Dynamic Range</td>
<td></td>
</tr>
<tr>
<td>Frequency Response (–3 dB)</td>
<td></td>
</tr>
<tr>
<td>Cross Axis Sensitivity</td>
<td></td>
</tr>
<tr>
<td>Output Noise</td>
<td></td>
</tr>
</tbody>
</table>
△ Safety Precautions (MEMS Gyro Sensors for Rollover detection/EWTS64G)

1. Soldering
   (1) Thickness of Solder Paste (Recommendation): 0.15 mm to 0.20 mm
   (2) Flux: Use non-corrosive rosin, and alcohol-based solvent with little chemical reaction.
   (3) Pre-heat: Control the temperature on PWB to be under 180°C and no longer than 120 s
   (4) Reflow Soldering condition: The maximum temperature on PWB is 260°C
   (5) Atmospheric Temperature: The atmospheric temperature should be under 360°C
   (6) Cooling: To avoid deterioration of the sensor due to heat, immediately cool the sensor with blown air.
   (7) Number of times it can be Reflow Soldered: Once
   (8) Hand soldering (recommendation): a) Use a 20 W or less soldering iron at less than 350°C.
                                b) Soldering time: within 3 s

2. Washing
   Do not wash.

3. Handling
   (1) Handle with care. Do not drop or apply any strong impact to the sensor this may degrade some performances.
   (2) Do not store under the following conditions, they may degrade some performances and solderability.
       a) Relative humidity of more than 85 %
       b) Atmospheres of corrosive gas (Cl₂, H₂S, NH₃, NOₓ, SO₂ etc.)
       c) Long term storage of over 3 months after delivery
       Do not store the package under severe load and stress.

4. Pattern layout of the circuit board
   See the following recommended pattern design (mm).

5. Layout
   The sensor has a slight zero point temperature drift due to surrounding conditions. Locate the sensor with care of the following items.
   (1) Do not locate the sensor close to heat radiating objects such as power transistors.
   (2) Do not locate the sensor where it will be affected by heat convection.

6. The application method of a coating agent.
   Please apply by the spray system about a coating agent. (Recommendation)
   Dip coating of a coating agent is disapproval.

7. Vibration from outside
   If the PWB with the sensor is resonant to frequencies caused by external vibrations, take the following items into consideration.
   (1) Rigid glass-epoxy circuit board is recommended. Locate the sensor close to the mounting screws of the PWB. (Since tuning fork part has a resonating point (detuning frequency) between 300 to 900 Hz, vibration evaluation in actual use is necessary.)
   (2) Locate other parts so that they will not touch the sensor directly due to external vibration.
   (3) Do not allow the mounting screws in the circuit board to become loose.
       * Perform a vibration test and carefully check the condition of the sensor attached to the unit.

Design and specifications are each subject to change without notice. Ask factory for the current technical specifications before purchase and/or use.
Should a safety concern arise regarding this product, please be sure to contact us immediately.

02      Jul. 2015
8. Recommended circuit

![Circuit Diagram]

(1) Be sure to use 100 kΩ load resistors.

(2) The sensor does not have a power-supply backup capacitor. Insert a backup capacitor in the power supply line close to the sensor when power supply is far or the power is supplied through connectors. In case of instant power break, vibration of the tuning fork stops and takes 0.5 second to reboot.

(3) Reverse voltage or over-voltage of more than 6.3 V may destroy the sensor.

(4) When the sensor signal goes to an A/D converter, use the same 5 V power supply for both the sensor and the A/D converter.

(5) EMC characteristics depend on whether the shield case is power grounded or case grounded. Choose which one after evaluating the assembled set.

9. Limited Warranty

Great attention has been paid to the quality of this sensor. As a failure mode, however, zero point output, sensitivity error, instability, or the like may occur. For a single failure of the sensor, study the influence of the whole circuit in advance.

(1) Install the following systems for a failsafe design to ensure safety if these products are to be used in equipment where a defect in these products may cause the loss of human life or other significant damage, such as damage to vehicles (automobile, train, vessel), traffic lights, medical equipment, aerospace equipment, electric heating appliances, combustion/gas equipment, rotating equipment, disaster/prevention equipment, nuclear apparatus, and machine tools.

- Systems equipped with a protection circuit and a protection device
- Systems equipped with a redundant circuit or other system to prevent an unsafe status in the event of a single fault

(2) If questions about the safety of this product arise, please do not hesitate to contact our company and be sure to perform the technical assessment.
Guidelines and precautions regarding the technical information and use of our products described in this online catalog.

- If you want to use our products described in this online catalog for applications requiring special qualities or reliability, or for applications where the failure or malfunction of the products may directly jeopardize human life or potentially cause personal injury (e.g. aircraft and aerospace equipment, traffic and transportation equipment, combustion equipment, medical equipment, accident prevention, anti-crime equipment, and/or safety equipment), it is necessary to verify whether the specifications of our products fit to such applications. Please ensure that you will ask and check with our inquiry desk as to whether the specifications of our products fit to such applications use before you use our products.

- The quality and performance of our products as described in this online catalog only apply to our products when used in isolation. Therefore, please ensure you evaluate and verify our products under the specific circumstances in which our products are assembled in your own products and in which our products will actually be used.

- If you use our products in equipment that requires a high degree of reliability, regardless of the application, it is recommended that you set up protection circuits and redundancy circuits in order to ensure safety of your equipment.

- The products and product specifications described in this online catalog are subject to change for improvement without prior notice. Therefore, please be sure to request and confirm the latest product specifications which explain the specifications of our products in detail, before you finalize the design of your applications, purchase, or use our products.

- The technical information in this online catalog provides examples of our products' typical operations and application circuits. We do not guarantee the non-infringement of third party's intellectual property rights and we do not grant any license, right, or interest in our intellectual property.

- If any of our products, product specifications and/or technical information in this online catalog is to be exported or provided to non-residents, the laws and regulations of the exporting country, especially with regard to security and export control, shall be observed.

<Regarding the Certificate of Compliance with the EU RoHS Directive/REACH Regulations>

- The switchover date for compliance with the RoHS Directive/REACH Regulations varies depending on the part number or series of our products.

- When you use the inventory of our products for which it is unclear whether those products are compliant with the RoHS Directive/REACH Regulation, please select "Sales Inquiry" in the website inquiry form and contact us.

We do not take any responsibility for the use of our products outside the scope of the specifications, descriptions, guidelines and precautions described in this online catalog.